

Prediction of shear capacity of steel channel sections using machine learning algorithms

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Abstract

This study presents the application of popular machine learning algorithms in prediction of the shear resistance of steel channel sections using experimental and numerical data. Datasets of 108 results of stainless steel lipped channel sections and 238 results of carbon steel LiteSteel sections were gathered to train machine learning models including support vector regression (SVR), multi-layer perceptron (MLP), gradient boosting regressor (GBR), and extreme gradient boosting (XGB). The cross-validation with 10 folds has been conducted in the training process to avoid over-fitting. The optimal hyperparameter combinations for each machine learning model were found during the hyperparameter tuning process and four performance indicators were used to evaluate the performance of the trained models. The comparison results suggest that all four implemented machine learning models reliably predict the shear capacity of both stainless steel lipped channel sections and carbon steel LiteSteel sections while the implemented SVR algorithm is found to be the best performing model. Moreover, it is shown that the implemented machine learning models exceed the prediction accuracy of the available design equations in estimating the shear capacity of steel channel sections.

Keywords: Channel sections, Shear capacity, Design rules, Machine learning

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1. Introduction

Light gauge cold-formed steel elements have gained interest over heavier hot-rolled sections in recent times as cost effective, highly efficient structural solutions [1]. Szewczak et al. [2] reported that the use of thin-walled steel sections have reduced the steel consumption by up to 50%, construction time by up to 60% and construction costs by up to 25%, compared to conventional hot-rolled sections. Cold-formed lipped channel beams (LCBs) and LiteSteel beams (LSBs) are most utilised as primary and secondary load-carrying structural elements such as roof purlins, wall studs, steel framing, truss beams, and floor joists and bearers [1, 3–5].

Stainless steel is an evolving cold-forming material in the construction industry due to its outstanding material properties. Higher chromium content in stainless steel acts as a protective layer against oxidation and corrosion [6–8]. The unique characteristics that cold-formed stainless steel sections feature include corrosion resistance, fire and heat resistance, durability, good toughness and fatigue properties, high strength to weight ratio, simple fabrication and handling, and recyclability [4, 8]. The application of stainless steel in the construction industry has been increased with the improved insight of its advantages such as savings from corrosion-resistant coatings, reduced inspection frequency, maintenance, downtime and replacement costs, and a transition towards sustainability. However, stainless steel has become less popular in structural applications due to the high initial material cost of stainless steel structural components when compared to carbon steel. Therefore, the accurate prediction of resistance of stainless steel sections is of paramount importance.

Many research studies have been conducted to investigate the shear performance of cold-formed channel sections in the recent past, both experimentally and numerically. Keerthan and Mahendran [9, 10] performed experimental studies on the shear behaviour of carbon steel LSBs and LCBs, and the shear design equations have been proposed based on North American specifications [11]. Furthermore, Keerthan and Mahendran [1, 12, 13] developed finite element (FE) models to predict the non-linear shear behaviour of carbon steel channels, including their elastic buckling and ultimate shear capacities with precision. In addition, Pham and Hancock [14–17] conducted both experimental and numerical investigations on the shear response of plain and stiffened carbon steel channel sections. Since there was an absence of comprehensive investigations on the shear behaviour of cold-formed stainless

38 steel LCBs to date, Dissanayake et al. [18] performed a combined experi-
39 mental and numerical study to predict the shear behaviour and strength of
40 stainless steel LCBs. Dissanayake et al. [19] also conducted FE investigations
41 to assess the shear and elastic shear buckling behaviours of the longitudinally
42 stiffened stainless steel LCBs. Ishqy et al. [6] studied the effect of unrein-
43 forced circular web openings on the shear behaviour of cold-formed stainless
44 steel LCBs numerically. Moreover, Sonu and Singh [20, 21] examined the
45 shear performance of lean duplex stainless steel rectangular hollow beams
46 using FE analyses. These studies involve the modification of existing design
47 rules considering the inelastic reserve capacity and strain hardening effect of
48 stainless steel to enhance the shear capacity prediction accuracy of European
49 standards for stainless steel [22] and the Direct Strength Method (DSM).

50 In recent years, the artificial intelligence methods, especially machine
51 learning, have gained a lot of attention in civil engineering applications by
52 offering viable solutions for complex problems such as prediction, classifi-
53 cation and optimisation [23]. It is evident that the utilization of machine
54 learning in civil engineering has fuelled many visions and hopes for future re-
55 search and development [24–26]. The machine learning methods can perform
56 exceptionally well in prediction the non-linear relationships among the inputs
57 and outputs which are difficult to formulate otherwise and do not necessarily
58 require large amount of data [24]. Also, the machine learning models are
59 computationally efficient and at the same time can be expandable to provide
60 robust predictions even with large amount of data. The application of ma-
61 chine learning has been featured in numerous civil and structural engineering
62 research publications [26–29].

63 The machine learning prediction models have been utilised in many civil
64 and structural engineering research areas. Fonseca et al. [30] have investi-
65 gated the possibility of employing experimental and numerical data to train
66 an artificial neural network (ANN) to predict the patch load resistance. The
67 ANN models have also been developed using finite element data to pre-
68 dict the deflections for composite beams by Sakr and Sakla [31] and for
69 steel-concrete composite bridges by Tadesse et al. [32]. A particle swarm
70 optimization-based neural network was proposed to predict the failure of
71 multi-storied reinforced concrete buildings by Chatterjee et al. [33]. Ab-
72 dollahzadeh and Ghobadi [34] proposed a neural network model to predict
73 the hysteretic behaviour of perforated steel plate shear walls. The neural
74 network-based models were also developed using finite element data to esti-
75 mate the stress concentration factors for multi-planar tubular joints by Chiew

76 et al. [35] and for welded joints by Dabiri et al. [36, 37]. The computational
77 prediction models including genetic programming were developed using test
78 results for moment-rotation behaviour of boltless steel connections by Shah
79 et al. [38]. In another study, Bağcı [39] predicted the moment-curvature
80 relationship of reinforced concrete sections using ANN. Jakubek [40] trained
81 multi-layer perceptron and fuzzy weights neural network models to predict
82 the load capacity of eccentrically loaded reinforced concrete columns. Nader-
83 pour et al. [41] used different soft computing methods for the compressive
84 strength prediction of FRP-confined reinforced concrete columns. Hadi [42]
85 conducted optimization studies on concrete beams using back-propagation
86 neural networks. The use of single and ensemble machine learning methods
87 in prediction of long-term deflections of reinforced concrete beams were in-
88 vestigated by Pham et al. [43]. Erdem [44] applied the ANNs to predict
89 the moment capacity of reinforced concrete slabs in fire. McKinney and Ali
90 [45] have employed supervised ANNs in spalling classification and failure pre-
91 diction of high strength concrete columns subjected to fire. Also, a genetic
92 algorithm optimized back-propagation neural network was developed for the
93 determination of flexural capacity of postfire reinforced concrete beams by
94 Cai et al. [46]. Moreover, Shen et al. [47] have proposed a new material
95 design method for ultra-high strength stainless steel using machine learning
96 algorithms. And Mu et al. [48] have devised an ensemble machine learn-
97 ing model to predict the strain-induced martensite in austenitic steels. Vu
98 et al. [49] have proposed an efficient framework based on the gradient tree
99 boosting algorithms for the strength prediction of the concrete filled steel
100 tubular columns. A gradient tree boosting model was also used by Truong
101 et al. [50] to evaluate the safety of steel trusses through prediction of the
102 load-carrying capacity and the displacement of the structure. Kim et al. [51]
103 have assessed the efficiency of different machine learning models to predict
104 and classify the load-carrying resistance of steel frames. It is of note that the
105 most of these applications of machine learning models have outperformed the
106 existing design methods in providing accurate predictions.

107 The use of machine learning prediction models in these particular appli-
108 cation fields is explained by the availability of the large quantity of initial
109 data on which the learning algorithm or the network is trained and most
110 of the above applications provide reasonably easy access to large datasets,
111 for example, through repeated laboratory experiments or computer mod-
112 elling [52]. In addition, the application of machine learning models in civil
113 engineering has dealt with structural health monitoring, damage detection

114 of structures, structural optimization, and structural parameter identifica-
 115 tion. The structural health monitoring and material property modelling of
 116 concrete have received significant attention in the recent past among these
 117 machine learning applications in civil engineering [24]. The machine learning
 118 algorithms have also been used to classify the failure modes of ultra-high
 119 performance concrete beams [53]. Fig. 1 illustrates the typical workflow of
 120 machine learning processes.

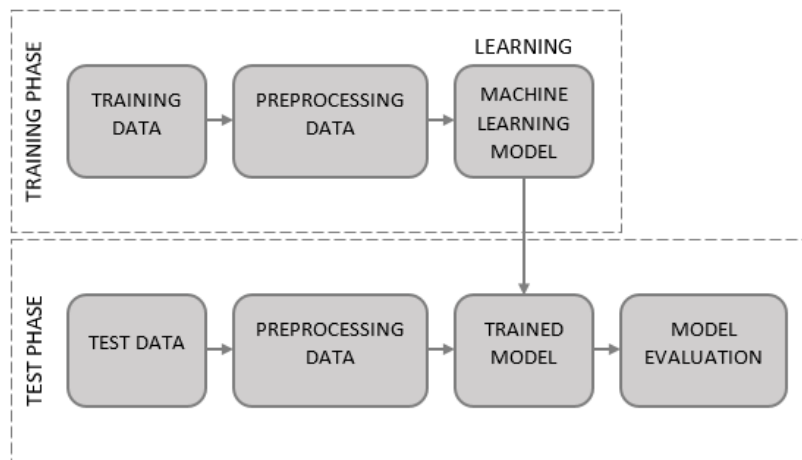


Figure 1: Typical workflow of machine learning processes.

121 In terms of tackling structural engineering problems, especially in or-
 122 der to analyse the structural behaviours, data-driven approaches have been
 123 used. To estimate material properties, researchers have established predic-
 124 tive models which minimise the prediction error between the actual data
 125 collected from experiments and models [54]. Machine learning applications
 126 typically use classification and prediction to solve problems. As machine
 127 learning enables training of algorithms and testing them based on available
 128 datasets, the mastery of models, basic statistics and availability of reliable
 129 data are essential to make most accurate predictions [25].

130 Although many past studies have utilised machine learning prediction
 131 models for design and performance prediction of reinforced concrete and hot-
 132 rolled steel structures, there are very few articles which focus on the applica-
 133 tion of machine learning to predict the behaviour of cold-formed sections. In
 134 particular, past studies have not attempted to investigate the application
 135 of machine learning models in prediction of the shear strength of cold-formed

136 stainless steel and carbon steel channel sections. The accurate determination
137 of section strengths plays vital role in planning and design of steel structures.
138 The available machine learning models can be easily implemented to handle
139 large number of data to make robust predictions. Therefore, considering the
140 benefits of using machine learning prediction models in structural design,
141 this research study aims to analyse the applicability of machine learning in
142 prediction of the shear capacity of cold-formed stainless steel LCBs and car-
143 bon steel LSBs to develop efficient machine learning prediction tools which
144 will potentially help to lower the costs associated with experiments and FE
145 simulations.

146 **2. The development of database**

147 A database of compiled results is required for the successful implemen-
148 tation of machine learning algorithms. Hence, a literature survey has been
149 undertaken to collect the results from experimental and FE studies on the
150 shear capacity of cold-formed stainless steel and carbon steel beams. This
151 section presents a brief review of experimental and FE modelling methods
152 used herein followed by a summary of the collected database.

153 *2.1. Overview of experimental and FE analysis*

154 Dissanayake et al. [18] and Keerthan and Mahendran [9, 12] have in-
155 vestigated the shear behaviour of cold-formed stainless steel LCBs and cold-
156 formed carbon steel LSBs, respectively. The cross-sections of a LCB section
157 and a LSB section are illustrated in Fig. 2. The aspect ratio, which is de-
158 fined as the clear shear span (a) divided by the clear web height (d_1), governs
159 the shear failure. It is considered that a shear dominant failure occurs when
160 this ratio is equal to unity. For stainless steel LCB sections, Dissanayake et
161 al.'s [18] test programme included aspect ratio of 1.0 while for LSB sections,
162 Keerthan and Mahendran's [9] test programme included aspect ratio of 1.0
163 and 1.5. Three-point loading test arrangement with two shear spans was
164 used in both studies. The shear capacity was found from the peak load of
165 the load-displacement response. More details about the three-point loading
166 test programmes of cold-formed sections can be found from similar experi-
167 mental studies [10, 15, 16, 55]. These experimental studies have been further
168 extended using validated FE models.

169 Keerthan and Mahendran [12] and Dissanayake et al. [18] have developed
170 non-linear FE models in the advanced FE modelling software, ABAQUS [56].

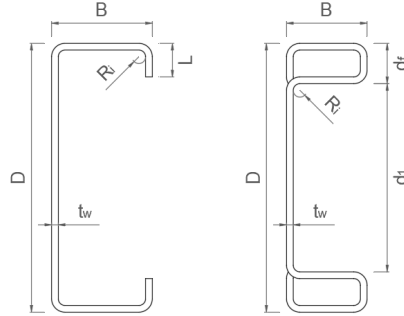


Figure 2: Cross-sections of LCB and LSB sections with key dimensions.

171 The developed FE models were validated against the experimental results in
 172 terms of shear capacity, failure mode and load-displacement response. Sub-
 173 sequently, parametric FE analysis was performed changing the dimensional
 174 and mechanical parameters. The S4R shell elements available in ABAQUS
 175 [56] element library were used to develop the FE model components of both
 176 the steel channel section and the web side plates. The web side plates were
 177 modelled with shell elements and a higher thickness value was assigned to
 178 simulate the rigid body behaviour. These web side plates were connected
 179 using tie constraints option. A mesh size of $5 \text{ mm} \times 5 \text{ mm}$ was employed to
 180 flat parts and a mesh size of $1 \text{ mm} \times 5 \text{ mm}$ was employed to corner parts
 181 of the channel sections. Meanwhile, a coarser mesh size was assigned to the
 182 web side plates as the shear behaviour of the channel is not influenced by
 183 the web side plates. Fig. 3 depicts the FE mesh and boundary conditions
 184 employed in the FE models for LCBs.

185 The accurate material modelling of cold-formed carbon steel and stain-
 186 less steel is required to obtain the actual behaviour from the FE model. The
 187 stress-strain response of carbon steel was taken as a bi-linear model with per-
 188 fect plasticity using nominal yield strength. However, stainless steel exhibits
 189 a considerable degree of strain hardening as well as strength enhancements
 190 due to cold-working. Therefore, the material model proposed by Arrayago et
 191 al. [57], which is based on the modified Ramberg-Osgood model, was used.
 192 The strength enhancements were assigned to the corner regions of the model
 193 as per the Cruise and Gardner's [58] recommendations. Moreover, the initial
 194 geometric imperfections were considered in the FE model superimposing the
 195 critical elastic buckling analysis modes. An illustration of obtained FE shear
 196 failure mode for LCB is also displayed in Fig. 3. For further details related

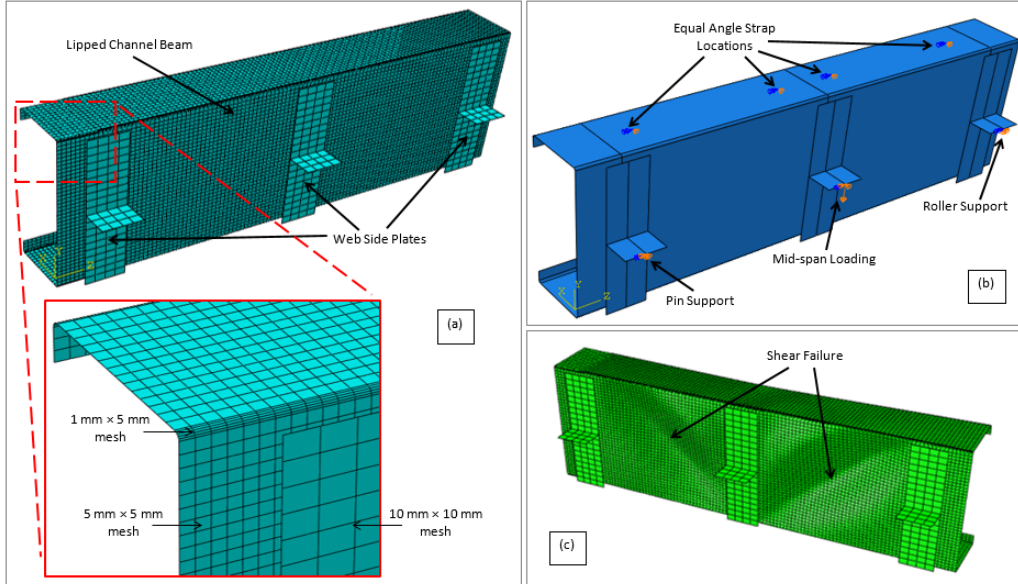


Figure 3: FE modelling of LCB section: (a) Mesh, (b) Boundary conditions, and (c) Failure mode.

197 to the FE modelling of cold-formed sections, similar numerical work can be
 198 referred [1, 13, 14, 17, 19, 59–61].

199 2.2. Collected datasets

200 Dissanayake et al. [18] and Keerthan and Mahendran [9, 12] have gen-
 201 erated a wide range of data using experimental and FE analysis methods
 202 as described in the previous section. All the related data from their studies
 203 were collated to form a database with input and output features. The details
 204 of the collected data are discussed herein.

205 For cold-formed stainless steel LCB sections, 108 results were collected
 206 in total from Dissanayake et al.'s [18] study. This includes 8 shear test
 207 results and 100 numerical parametric study results. The dataset consists of
 208 various geometric and material parameters as input features. The considered
 209 geometric input features of stainless steel LCBs include web depth (D), flange
 210 width (B), lip height (L), and web thickness (t_w). Also, aspect ratio (a/d_1)
 211 and a slenderness measure of the web (d_1/t_w) are taken into account. The
 212 adopted material property features include the yield strength (f_y) and the
 213 ultimate strength (f_u) of stainless steel. And, the output feature is the shear

214 strength (V) of LCBs. Table 1 reports the key statistics of input and output
 215 features of LCBs dataset.

Table 1: Key statistics of cold-formed stainless steel LCBs dataset

	#samples		D (mm)	B (mm)	L (mm)	t_w (mm)	a/d_1	d_1/t_w	f_y (MPa)	f_u (MPa)	V (kN)
Experiment	8	Min	99.48	50.0	15.5	1.18	1.0	45.97	253.9	725.3	18.5
		Max	200.98	75.5	16.5	1.99	1.0	163.55	253.9	725.3	47.1
FE	100	Min	100.0	50.0	15.0	1.0	1.0	17.2	230.0	540.0	12.93
		Max	250.0	75.0	15.0	5.0	1.0	244.0	500.0	700.0	356.07
Overall	108	Min	99.48	50.0	15.0	1.0	1.0	17.2	230.0	540.0	12.93
		Max	250.0	75.5	16.5	5.0	1.0	244.0	500.0	725.3	356.07

216 The gathered stainless steel LCBs dataset covers a range of parameters
 217 that can be seen in practice. For an instance, the depth of the LCBs ranges
 218 from 99.48 mm to 250 mm. The thickness of the LCBs is varying between
 219 1 mm and 5 mm. The minimum and maximum values of the average yield
 220 strength of the LCBs are 230 MPa and 500 MPa, respectively. Meanwhile,
 221 the corresponding ultimate strength values range from 540 MPa to 725.3
 222 MPa.

223 For cold-formed carbon steel LSB sections, 238 results were collected in
 224 total including 25 shear test results and 213 parametric FE results from the
 225 respective studies [9, 12]. Similar to the previously discussed LCBs dataset,
 226 the considered geometric dimensions of LSBs include web depth (D), flange
 227 width (B), clear web height (d_1), and web thickness (t_w). In addition, it con-
 228 siders aspect ratio (a/d_1) and a slenderness parameter of the web (d_1/t_w).
 229 The yield strength (f_y) of carbon steel is the only material property con-
 230 sidered. Similarly, the shear strength (V) of LSBs is taken as the output
 231 feature. The key statistics of input and output features of LSBs dataset are
 232 summarised in Table 2.

233 As can be seen, Table 2 also demonstrates that the collated dataset covers
 234 a full spectrum of practically used LSB sections in light gauge steel construc-
 235 tion. For an instance, the depth of the LSBs ranges from 125 mm to 300
 236 mm. The thickness of the LSBs is varying between 1.5 mm and 3 mm. The
 237 minimum and maximum values of the average yield strength of the LSBs
 238 from the collected data are 250 MPa and 459.7 MPa, respectively.

239 It is also of note that both the collected stainless steel and carbon steel
 240 datasets cover the elastic and inelastic shear buckling, and shear yielding
 241 failure behaviours. Furthermore, both datasets include a wide range of com-

Table 2: Key statistics of cold-formed carbon steel LSBs dataset

	#samples		D (mm)	B (mm)	d_1 (mm)	t_w (mm)	a/d_1	d_1/t_w	f_y (MPa)	V (kN)
Experiment	25	Min	125.0	45.0	95.2	1.58	1.0	49.07	422.6	45.8
		Max	300.0	75.0	262.3	2.51	1.6	133.14	459.7	143.7
FE	213	Min	150.0	45.0	119.7	1.5	1.0	60.0	250.0	29.8
		Max	300.0	75.0	260.8	3.0	1.5	163.0	450.0	173.0
Overall	238	Min	125.0	45.0	95.2	1.5	1.0	49.07	250.0	29.8
		Max	300.0	75.0	262.3	3.0	1.6	163.0	459.7	173.0

242 commercially available cross-sectional dimensions and material grades covering
 243 a range of cross-section slenderness values and strengths. Therefore, the
 244 collected database is found to be handy in developing machine learning al-
 245 gorithms that could be more promising than the existing code provisions to
 246 predict the shear capacities of stainless steel LCBs and carbon steel LSBs.

247 3. Review of design equations for cold-formed sections

248 The currently available design provisions for cold-formed sections are re-
 249 viewed in this section. The shear design equations given in European stan-
 250 dards for stainless steel, EN1993-1-4 [22] and the direct strength method
 251 (DSM) shear provisions in North American specifications for cold-formed
 252 steel members, AISI S100 [11] have been modified by Dissanayake et al. [18]
 253 to enhance the shear resistance prediction accuracy of cold-formed stainless
 254 steel LCBs. Also, Keerthan and Mahendran [12] have revised the DSM shear
 255 design provisions in AISI S100 [11] considering the cold-formed carbon steel
 256 LSBs. These proposed design provisions are found to be more accurate than
 257 the codified design provisions. Therefore, the revised provisions were adopted
 258 and would be used to compare and assess the prediction performance of the
 259 machine learning models in Section 5.

260 3.1. EN1993-1-4 shear design rules

European standards for stainless steel, EN1993-1-4 [22] provide a separate set of shear design equations which are to be referred together with European standards for plated steel elements, EN1993-1-5 [62]. Following these standards, the shear resistance of a section ($V_{b,Rd}$) is taken as the summation of the shear buckling resistance of the section web ($V_{bw,Rd}$) and the flange

contribution to the shear resistance of the section ($V_{bf,Rd}$) as follows

$$V_{b,Rd} = V_{bw,Rd} + V_{bf,Rd} \leq \frac{\eta f_{yw} h_w t_w}{\sqrt{3} \gamma_{M1}}, \quad (1)$$

where f_{yw} is the yield strength of the section web, h_w is the web depth, and t_w is the web thickness. γ_{M1} is the partial safety factor and a value of $\eta = 1.2$ is recommended. The shear buckling resistance of the section web ($V_{bw,Rd}$) can be calculated as

$$V_{bw,Rd} = \frac{\chi_w f_{yw} h_w t_w}{\sqrt{3} \gamma_{M1}}, \quad (2)$$

where χ_w is the shear buckling reduction factor of the web. EN1993-1-4 [22] provides a separate set of expressions for this shear buckling reduction factor (χ_w) of section webs with rigid end posts and they are expressed as follows

$$\chi_w = \eta \quad \text{for } \bar{\lambda}_w \leq \frac{0.65}{\eta}, \quad (3a)$$

$$\chi_w = \frac{0.65}{\bar{\lambda}_w} \quad \text{for } \frac{0.65}{\eta} < \bar{\lambda}_w < 0.65, \quad (3b)$$

$$\chi_w = \frac{1.56}{0.91 + \bar{\lambda}_w} \quad \text{for } \bar{\lambda}_w \geq 0.65, \quad (3c)$$

261 where $\bar{\lambda}_w$ is the slenderness of the section web.

Following a number of experimental and numerical studies on cold-formed stainless steel LCBs, Dissanayake et al. [18] have proposed a modification to Eq. (3) to increase the prediction accuracy. These modified expressions are expressed as follows

$$\chi_w = 2.1 \quad \text{for } \bar{\lambda}_w \leq 0.12, \quad (4a)$$

$$\chi_w = \frac{0.839}{\bar{\lambda}_w^{0.433}} \quad \text{for } 0.12 < \bar{\lambda}_w < 0.667, \quad (4b)$$

$$\chi_w = \frac{1.797}{1.13 + \bar{\lambda}_w} \quad \text{for } \bar{\lambda}_w \geq 0.667. \quad (4c)$$

262

263 3.2. The direct strength method (DSM)

The DSM has been adopted in North American specifications for cold-formed steel members, AISI S100 [11]. The nominal shear strength of a

section (V_n) with transverse web stiffeners are given as follows

$$\frac{V_n}{V_y} = 1 \quad \text{for } \lambda \leq 0.776, \quad (5a)$$

$$\frac{V_n}{V_y} = \left[1 - 0.15 \left(\frac{1}{\lambda^2} \right)^{0.4} \right] \left(\frac{1}{\lambda^2} \right)^{0.4} \quad \text{for } \lambda > 0.776, \quad (5b)$$

264 where λ is the section slenderness.

Dissanayake et al. [18] have also modified the DSM design equations given by Eq. (5) considering stainless steel LCBs. The modified DSM equations for the section nominal shear strength are expressed as follows

$$\frac{V_n}{V_y} = 2 \quad \text{for } \lambda \leq 0.122, \quad (6a)$$

$$\frac{V_n}{V_y} = \frac{0.795}{\lambda^{0.439}} \quad \text{for } 0.122 < \lambda \leq 0.592, \quad (6b)$$

$$\frac{V_n}{V_y} = \left[1 - 0.213 \left(\frac{1}{\lambda^2} \right)^{0.35} \right] \left(\frac{1}{\lambda^2} \right)^{0.35} \quad \text{for } \lambda > 0.592. \quad (6c)$$

265

In addition, extensive experimental and numerical investigations have been conducted by Keerthan and Mahendran [9, 12] on cold-formed carbon steel LSB sections. Based on these investigations, Keerthan and Mahendran [12] have revised the DSM shear design equations given by Eq. (5) aiming enhanced resistance predictions. The proposed DSM equations for the nominal shear strength of sections are stated as follows

$$\frac{V_n}{V_y} = 1 \quad \text{for } \lambda \leq 0.815, \quad (7a)$$

$$\frac{V_n}{V_y} = \left[1 - 0.15 \left(\frac{1}{\lambda^2} \right)^{0.5} \right] \left(\frac{1}{\lambda^2} \right)^{0.5} \quad \text{for } \lambda > 0.815. \quad (7b)$$

266

267 4. Machine learning algorithms

268 4.1. Overview

269 In this study, four well-known machine learning algorithms including sup-
270 port vector machine (SVM), multi-layer perceptron (MLP), and gradient

271 boosting machine (GBM) are used to predict the shear capacities of stainless
 272 LCBs and carbon steel LSBs. This section aims to provide a brief overview of
 273 these models and the details of the implementation process of these models
 274 in application to collected datasets.

275 4.1.1. Support vector machine

276 SVMs are categorised as supervised learning algorithms and can be utilised
 277 for classification and regression problems. Vapnik and his team [63, 64] have
 278 immensely contributed to the development of SVMs in the last decades.
 279 When applying these SVMs in solving regression related problems, it is
 280 known as support vector regression (SVR).

281 The fundamental concept behind SVMs is the non-linear mapping of the
 282 input vectors into a high dimensional feature space where the linear decision
 283 surface is constructed. The generalisation ability of the learning machine is
 284 ensured through the properties of the decision surface [64].

In other words, considering a set of training data $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\} \subset \chi \times \mathbb{R}$, the aim of ϵ -SVR [63] is to predict a flat decision function, $f(x)$ such that $f(x)$ is only allowed to deviate from the actual data y_i in the range of $(-\epsilon, \epsilon)$ for all the data in the training set [65]. For the case of linear decision function, $f(x)$ this can be expressed as

$$f(x) = \langle \omega, x \rangle + b \quad \text{with} \quad \omega \in \chi, \quad b \in \mathbb{R}, \quad (8)$$

285 where ω and b represent the weight and bias, respectively.

However, finding a decision function is not always possible as there could be data points in some datasets that are lying outside the feasible region [64, 65]. To address this issue, Cortes and Vapnik [64] have considered the “soft margin” loss function in SVMs and therefore slack variables ξ_i are introduced as illustrated in Fig. 4a. Then, setting the objective of flattening the decision function leads to the formulation of the optimisation problem that includes the slack variables ξ_i as follows [63]

$$\text{minimize} \quad \frac{1}{2} \|\omega\|^2 + C \sum_{i=1}^n (\xi_i), \quad (9a)$$

$$\text{subject to} \quad |y_i - \langle \omega, x \rangle - b| \leq \epsilon + \xi_i, \quad (9b)$$

$$\xi_i \geq 0, \quad (9c)$$

$$C > 0, \quad (9d)$$

286 where C determines both the flatness of the decision function $f(x)$ and the
 287 limit of the deviations that are larger than ϵ .

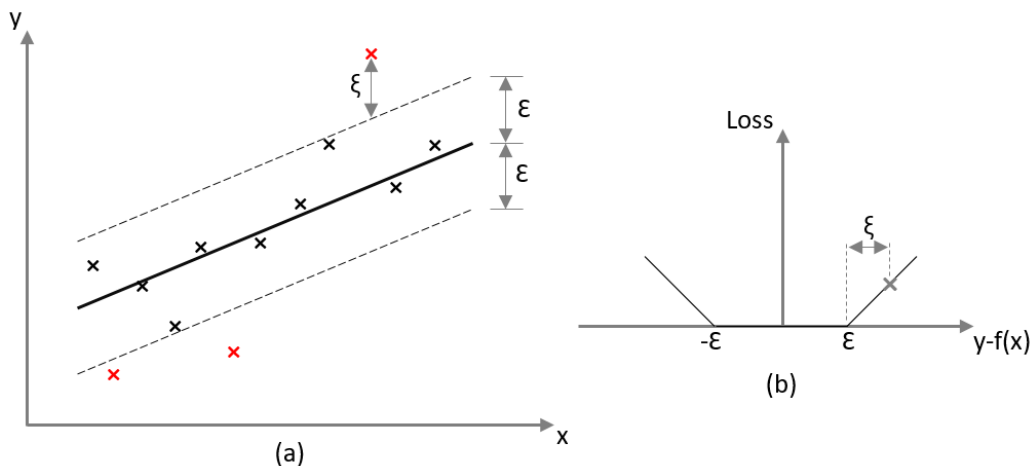


Figure 4: (a) “Soft margin” for linear SVM and (b) ϵ -insensitive loss function.

Only the points which deviate more than ϵ from the function contribute to the loss function in a linear fashion. This is known as ϵ -insensitive loss function $|\xi|_\epsilon$ [65] and this loss function which is illustrated in Fig. 4b is defined as

$$|\xi|_\epsilon = \begin{cases} 0 & \text{if } \xi \leq \epsilon, \\ \xi - \epsilon & \text{otherwise.} \end{cases} \quad (10)$$

288 Moreover, non-linear functions are introduced to SVM algorithms with
 289 the help of a kernel function when the linear decision function is no longer
 290 feasible. The kernel function defines the mapping of the training data from
 291 a lower dimensional feature space to a higher dimensional feature space. To
 292 achieve this, different types of kernel functions are employed [64, 65].

293 4.1.2. Multi-layer perceptron

294 MLP network is a feed-forward artificial neural network (ANN) which
 295 consists of layers of interconnected nodes. The layer with input features is
 296 named as input layer followed by one or more hidden layers and finally an
 297 output layer with one or more target outputs. Each layer consists of number
 298 of nodes known as neurons. The neurons are interconnected between layers
 299 [66]. The connection between two adjacent layers neurons are called weights

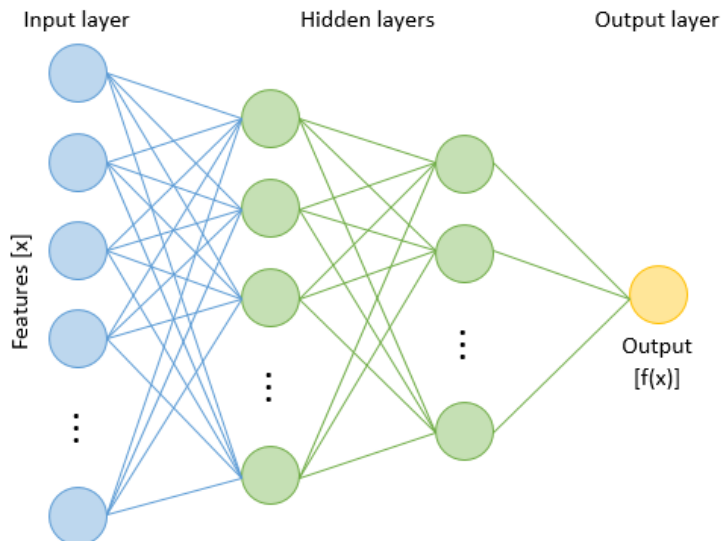


Figure 5: A multi-layer neural network with two hidden layers and a single output.

300 and biases are attached to each neuron. A multi-layer neural network with
 301 two hidden layers and a single output is illustrated in Fig. 5.

The input layer consists all the input features and feeds them to the network. Each neuron in hidden layers sends an output signal to the next layer in the form of a weighted linear summation modified by a non-linear transfer function known as activation function [67]. The output a_i of the i^{th} neuron in a particular hidden layer passed on to the next layer is defined as follows

$$a_i = f \left(\sum_{j=1}^n (w_{ij} a_j + b_i) \right), \quad (11)$$

302 where $f()$ is the activation function, w_{ij} is the weight between the j^{th} neuron
 303 in the previous layer and i^{th} neuron in the current layer, a_j is the output of
 304 the j^{th} neuron in the previous layer, and b_i is the bias of the i^{th} neuron in
 305 the current layer.

306 There are many different types of activation functions available. These
 307 includes linear, sigmoid, tanh and rectified linear units (ReLU) [67]. Fi-
 308 nally, the output layer transforms the values received from hidden layers into
 309 outputs.

310 MLP networks can be trained to learn the mapping function between the

311 input vector and the output vector using a set of training data. During the
 312 training process, an output is first obtained based on the initially assumed
 313 weights and biases when a training data set is presented to the network.
 314 Then, the error signal is calculated comparing the difference between the
 315 target and obtained outputs. This error signal is back-propagated through
 316 the network, and weights and biases are adjusted to minimise the overall
 317 error. A technique known as gradient descent is used to find the global
 318 minimum point on the error surface during the iterative training process
 319 [67].

320 4.1.3. Gradient boosting machine

321 GBMs are the ensemble models combining weak, base-learners in a se-
 322 quential manner to minimise the overall error of the whole ensemble. Fried-
 323 man [68] has first developed these boosting method in 1999. In GBMs, de-
 324 cision or regression trees are employed as base learners. During the learning
 325 process, a new weak, base learner is added to the model at the each iteration
 326 step. The new weak, base learner is trained to reduce the overall error of the
 327 ensemble at that point [69]. The sequential adding of new base learners is
 328 repeated until a desirable accuracy is achieved. This step by step addition
 329 of decision trees to the ensemble model at the each iteration to reduce the
 330 overall error to form a strong tree ensemble model is illustrated from Fig. 6.

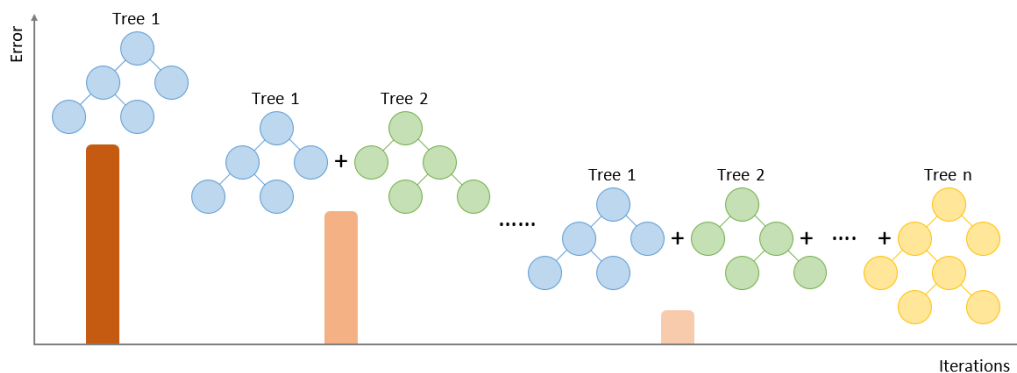


Figure 6: Gradient tree boosting machines.

In GBMs the error of the ensemble model is also known as the loss function. A number of loss functions are supported by GBMs and sometimes a case specific loss functions can be implemented [69]. Consider a vector

input $x = \{x_1, x_2, \dots, x_n\}$ and its output y . The output is dependent of input through function f . The aim of GBM algorithm is to find an estimated function $F(x)$ between inputs and the respective output such that the loss function $\Psi(y, f)$ is minimised. This can be expressed as follows

$$F(x) = \arg \min_{f(x)} \Psi(y, f(x)). \quad (12)$$

In the ensemble model, the step-wise addition of the function in the iterative process for N number of iterations is given as

$$F_N(x) = \sum_{i=0}^N F_i(x), \quad (13)$$

331 where the initial estimation is $F_0(x)$.

332 When it comes to regression problems, gradient boosting regressor (GBR)
333 and extreme gradient boosting (XGB) algorithms can be applied. The im-
334 portance of XGB is that its high-scalability and at the same time, it performs
335 more efficiently compared to other common boosting models [70].

336 *4.2. Model implementation*

337 Four machine learning models including SVR, MLP, GBR, and XGB were
338 implemented in Python for the shear resistance prediction of considered steel
339 sections. The implementation has been expanded from the codes provided by
340 Nguyen et al. [54] which was based on popular open source machine learning
341 libraries including `scikit-learn` [71] and `XGBoost` [70]. The details of data
342 pre-processing, cross-validation, and hyperparameter tuning are briefed in
343 this section.

344 *4.2.1. Pre-processing of data*

345 The pre-processing of data before it is being utilised for the training of a
346 particular model is vital. One aspect of data pre-processing is to normalise
347 the data into a uniform scale. The idea behind this is to avoid any domination
348 and numerical difficulty associated with large numerals during the training
349 phase of the model. In this study, all the input features were normalised to
350 the scale of 0 to 1. Then, the normalised input features were used to train
351 the models and the predicted outputs were transformed back to the original
352 scale for testing.

353 *4.2.2. Cross-validation*

354 The traditional approaches of cross-validation sometimes lead to over-
 355 fitting of the model in the training phase. The K-fold cross-validation method
 356 has been introduced to overcome this problem. Kohavi [72] has shown that
 357 choosing 10 number of folds provides the best results within a reasonable
 358 time. This approach has also been used in a number of published works
 359 [54, 73, 74]. Therefore, 10-fold cross-validation has been utilised in this study.

360 In the 10-fold cross-validation, the dataset is randomly divided into ten
 361 folds with approximately equal size. Then, while keeping one fold as the test set,
 362 the remaining nine folds are used for the training set. Once the first
 363 training is finished, in the next round, another fold is used as the test set,
 364 while remaining nine folds are used for the training. The process is repeated
 365 ten times to ensure that each fold is considered as the test set for one time
 366 and is contributed to the training set nine times. The final performance of
 367 the model is reported by taking the mean of ten training and testing rounds.
 368 This process of 10-fold cross-validation is illustrated in Fig. 7.

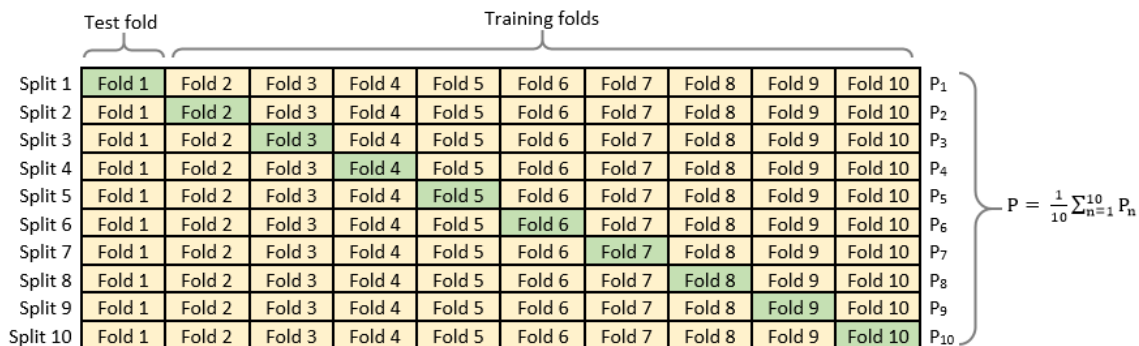


Figure 7: Cross-validation with ten folds.

369 *4.2.3. Hyperparameter tuning*

370 The performance of the most of the machine learning models is sensitive
 371 to the values of their hyperparameters [75–77]. During the hyperparameter
 372 tuning process, the optimal values for each hyperparameter are identified
 373 through the implemented machine learning algorithms. First, a set of values
 374 is predefined for each hyperparameter. Then, the values are assigned to
 375 the each hyperparameter from the predefined sets to form different hyper-
 376 parameter combinations. Thereafter, the machine learning model is trained

377 and evaluated for each of the hyperparameter combination, and the best
378 performing combination is found during the tuning.

379 5. Prediction results and discussion

380 The performance of the developed machine learning models are evalu-
381 ated using four performance indicators and then the performance of machine
382 learning algorithms are compared with the currently available design equa-
383 tions presented in Section 3.

384 5.1. Performance indicators

385 To evaluate the performance of different prediction approaches of shear
386 capacity of steel channel sections including the implemented machine learn-
387 ing algorithms and design equations, four performance indicators were incor-
388 porated in this study. These four indicators are linear correlation coefficient
389 (R), root mean square error (RMSE), mean absolute error (MAE), and mean
390 absolute percentage error (MAPE).

To calculate the linear correlation coefficient R, the coefficient of deter-
mination R^2 shall be determined as follows

$$R^2 = 1 - \frac{\sum_{i=1}^n (y - \hat{y})^2}{\sum_{i=1}^n (y - \bar{y})^2}, \quad (14)$$

391 where y denotes the actual data and \hat{y} represents the predicted value. \bar{y}
392 corresponds to the mean value of the actual data and n is the size of the
393 data sample. It is considered to be a good prediction, if the linear correlation
394 coefficient R is closer to 1.

Other performance indicators RMSE, MAE, and MAPE can be deter-
mined as follows

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_{i=1}^n (y - \hat{y})^2}, \quad (15a)$$

$$\text{MAE} = \frac{1}{n} \sum_{i=1}^n |y - \hat{y}|, \quad (15b)$$

$$\text{MAPE} = \frac{1}{n} \sum_{i=1}^n \left| \frac{y - \hat{y}}{y} \right| \times 100. \quad (15c)$$

395 The lower values of RMSE, MAE, and MAPE suggest that the error is less,
396 therefore a better prediction.

397 *5.2. Performance of the machine learning models*

398 *5.2.1. Cold-formed stainless steel LCBs*

399 Table 3 summarises the identified optimal combination of some hyperpa-
 400 rameters during the hyperparameter tuning process for each machine learning
 401 algorithm while Table 4 compares the performance of each algorithm using
 402 four performance indicators discussed above for the cold-formed stainless
 403 steel LCB sections. As can be seen from Table 4, all four algorithms demon-
 404 strate good performances in prediction of shear capacity of stainless steel
 405 LCBs and the implemented SVR machine learning model provides the best
 406 performance among four algorithms in all indicators.

Table 3: Hyperparameter combinations of machine learning algorithms in prediction of shear capacity of stainless steel LCBs

Method	Hyperparameter				
SVR	kernel	C	epsilon	gamma	-
	'rbf'	600	0.01	0.1	-
MLP	hidden_layer_sizes	solver	max_iter	alpha	-
	(100,60)	'lbfgs'	900	0.0001	-
GBR	n_estimators	max_depth	learning_rate	loss	min_samples_split
	1000	10	0.1	'lad'	10
XGB	n_estimators	max_depth	learning_rate	objective	-
	1400	2	0.35	'reg:linear'	-

Table 4: The performance of machine learning algorithms in prediction of shear capacity of stainless steel LCBs

Method	R	RMSE (kN)	MAE (kN)	MAPE (%)
SVR	0.999	2.76	2.32	4.03
MLP	0.998	4.13	3.18	5.95
GBR	0.997	5.53	4.19	4.47
XGB	0.997	5.51	4.31	6.86

407 The experimental and FE shear capacities of stainless steel LCBs are
 408 compared with the machine learning predictions for SVR and MLP models
 409 in Figs. 8 and 9, respectively. It can be seen that the model predictions are
 410 distributed closer to the actual data line and also the scatter of the predictions

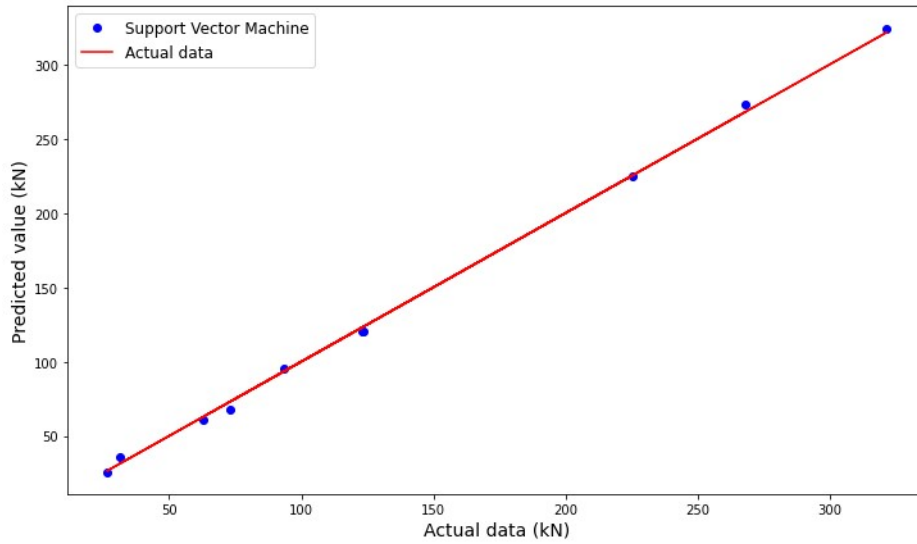


Figure 8: Performance of SVR model in prediction of shear capacity of stainless steel LCBS.

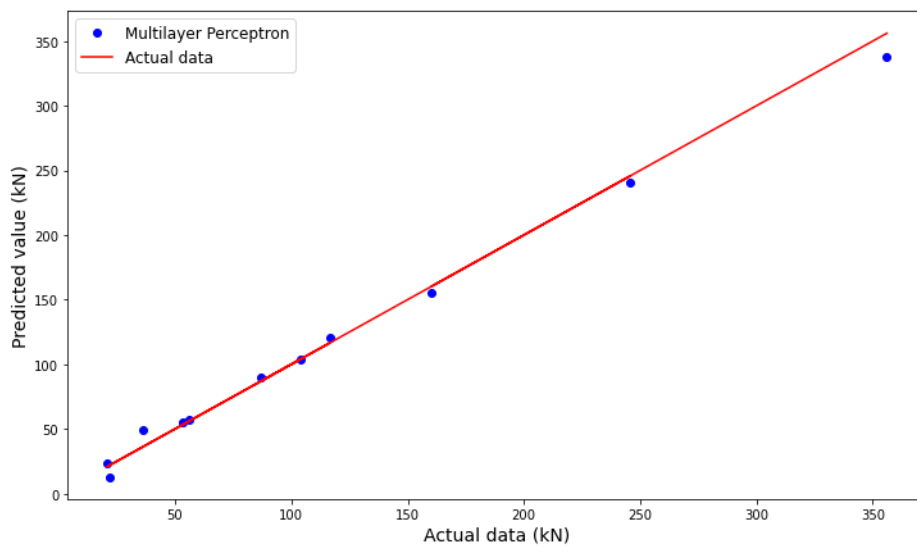


Figure 9: Performance of MLP model in prediction of shear capacity of stainless steel LCBS.

411 is very low. Therefore, the accuracy of machine learning predictions is further
 412 evidenced from these comparisons.

413 The relative importance of each input feature on the shear strength of
 414 the section was evaluated using the XGBoost library [70]. A higher value of
 415 relative feature importance implies that the impact of the particular input
 416 feature on the output is more significant. Fig. 10 illustrates the relative
 417 importance of each input feature on the shear strength of stainless steel
 418 LCB sections. From the figure, it can be observed that the input features
 419 yield strength f_y , web thickness t_w and section depth D have a considerably
 420 higher impact on the shear strength while yield strength f_y is being the most
 421 dominant among all features. On the other hand, a relatively lower feature
 422 importance can be seen from the features d_1/t_w , flange width B and lip
 423 height L . Interestingly, the ultimate strength f_u and aspect ratio have the
 424 least impact on the shear strength. There is no variation of aspect ratio in
 425 the input data set could be the reason for the lower rank of the feature in
 426 the relative importance. Also, the considered sections could have gained the
 427 shear strength before reaching the ultimate stress and therefore, this could
 428 result in ranking the ultimate strength f_u low.

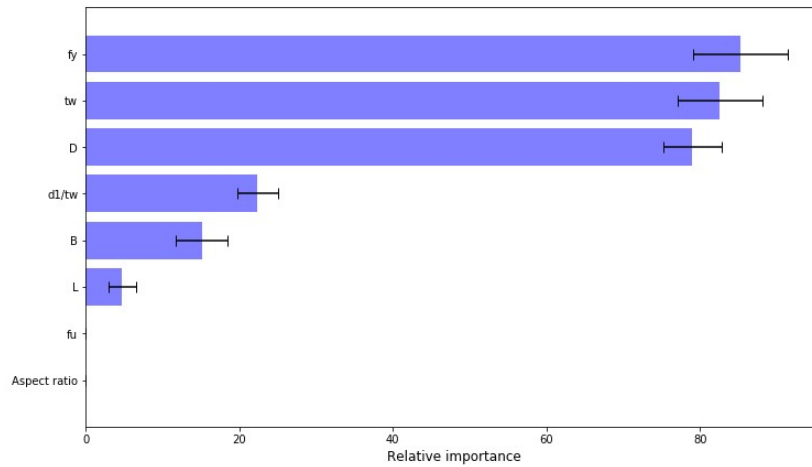


Figure 10: Relative importance of input features on the shear capacity of stainless steel LCBs.

429 5.2.2. Cold-formed carbon steel LSBs

430 The hyperparameter combinations which give the best predictions and the
 431 performance indicators of four machine learning algorithms are summarised

432 for the cold-formed carbon steel LSBs in Tables 5 and 6, respectively. The
 433 comparison results reported in Table 6 suggest that all four machine learning
 434 models are able to perform well in prediction of shear capacity of carbon steel
 435 LSBs as well. The implemented SVR model again offers the best agreement
 436 considering the overall performance.

Table 5: Hyperparameter combinations of machine learning algorithms in prediction of shear capacity of carbon steel LSBs

Method	Hyperparameter				
SVR	kernel	C	epsilon	gamma	-
	'rbf'	600	0.01	0.3	-
MLP	hidden_layer_sizes	solver	max_iter	alpha	-
	(300,100)	'lbfgs'	350	0	-
GBR	n_estimators	max_depth	learning_rate	loss	min_samples_split
	1500	4	0.15	'huber'	6
XGB	n_estimators	max_depth	learning_rate	objective	-
	800	2	0.15	'reg:linear'	-

Table 6: The performance of machine learning algorithms in prediction of shear capacity of carbon steel LSBs

Method	R	RMSE (kN)	MAE (kN)	MAPE (%)
SVR	0.999	1.26	0.95	1.43
MLP	0.998	1.65	1.05	1.39
GBR	0.997	2.19	1.49	1.89
XGB	0.996	2.06	1.35	1.74

437 Figs. 11 and 12 illustrate the comparison of experimental and FE shear
 438 strengths of carbon steel LSBs with the machine learning predictions for
 439 SVR and MLP algorithms, respectively. The distribution and lower scatter
 440 of predictions demonstrate a good agreement with actual data.

441 Fig. 13 is produced to evaluate the relative importance of considered
 442 input features on the shear strength of carbon steel LSB sections. The illus-
 443 tration indicates that the feature yield strength f_y has the highest influence
 444 on the shear strength of carbon steel LSBs which is a little less than twice of
 445 the importance of the second most influencing feature web thickness t_w . In
 446 contrast, the flange width B is found to be the feature with the least impact.

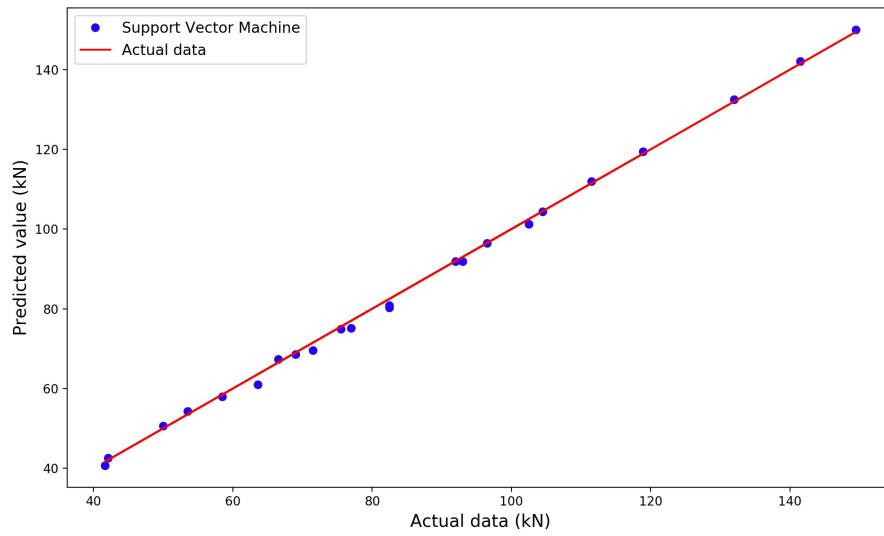


Figure 11: Performance of SVR model in prediction of shear capacity of carbon steel LSBs.

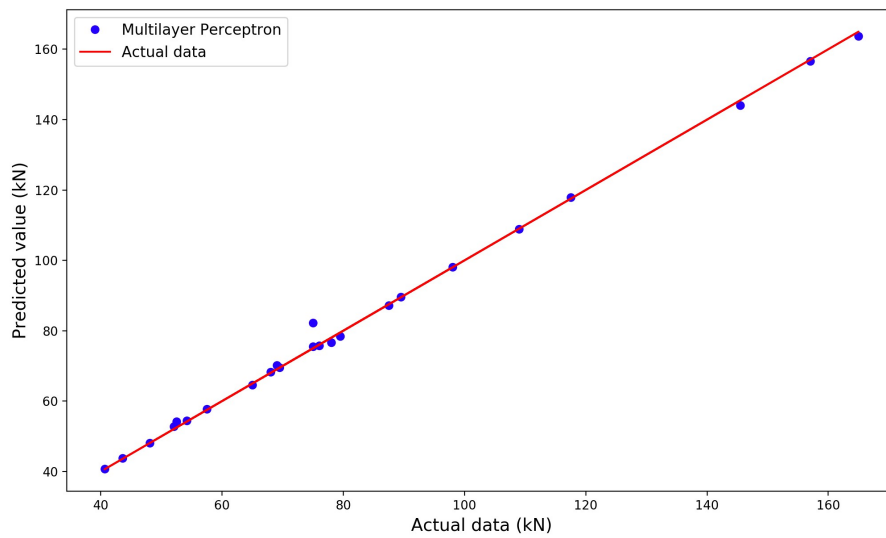


Figure 12: Performance of MLP model in prediction of shear capacity of carbon steel LSBs.

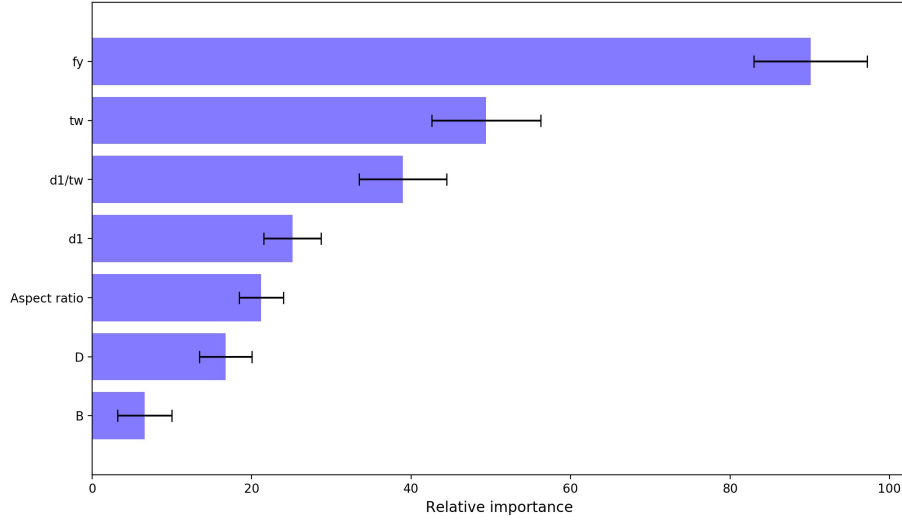


Figure 13: Relative importance of input features on the shear capacity of carbon steel LSBs.

447 *5.3. Performance of the design equations*

448 The performance of the design equations was also evaluated in prediction
 449 of shear capacity of stainless steel LCBs and carbon steel LSBs using four
 450 performance indicators. The modified shear design provisions for EN1993-1-
 451 4 [22] in Eq. (4) and the proposed DSM shear design equations in Eqs. (6-7)
 452 were incorporated herein.

453 Table 7 summarises the calculated performance indicators of these design
 454 equations for both stainless steel and carbon steel databases considered in
 455 this study. It can be observed that all four performance indicators provide
 456 fairly satisfactory results in prediction of shear strength of LCBs and LSBs
 457 using design equations.

Table 7: Performance of design equations in prediction of shear capacities of LCBs and LSBs

Problem	Design equation	R	RMSE (kN)	MAE (kN)	MAPE (%)
LCB	Eq. (4) [18]	0.998	3.78	2.85	3.56
	Eq. (6) [18]	0.998	4.16	3.29	4.28
LSB	Eq. (7) [12]	0.979	6.21	4.71	6.01

458 Furthermore, the experimental and FE shear capacities are compared
 459 with the design equation predictions. Figs. 14-16 present the comparisons

460 for Eq. (4), Eq. (6), and Eq. (7). The predictions of the best performing
461 machine learning model which is SVR are also included in these comparisons.

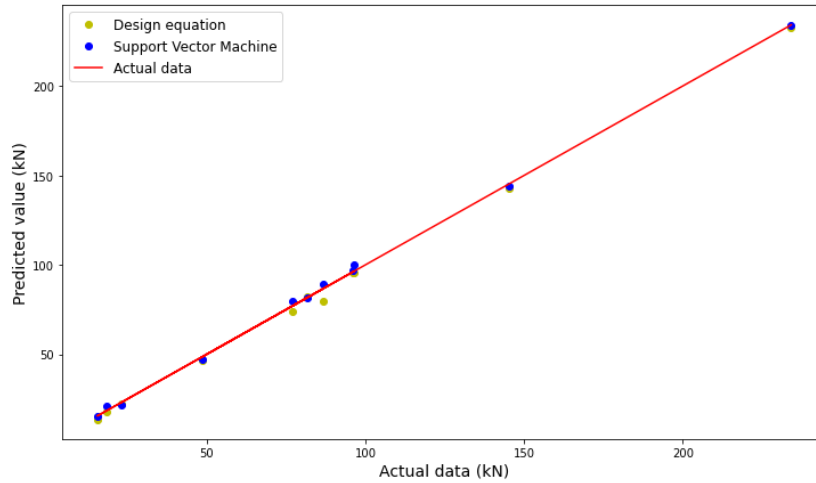


Figure 14: Comparison of the performance of Eq. (4) and SVR model in prediction of shear capacity of stainless steel LCBs.

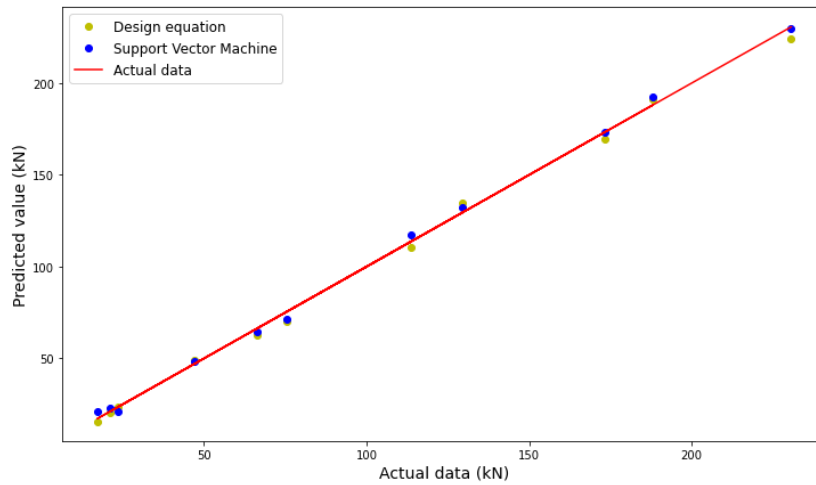


Figure 15: Comparison of the performance of Eq. (6) and SVR model in prediction of shear capacity of stainless steel LCBs.

462 It can be observed from Figs. 14 and 15 that the distribution and the
463 scatter of design equation predictions for stainless steel LCBs are marginally

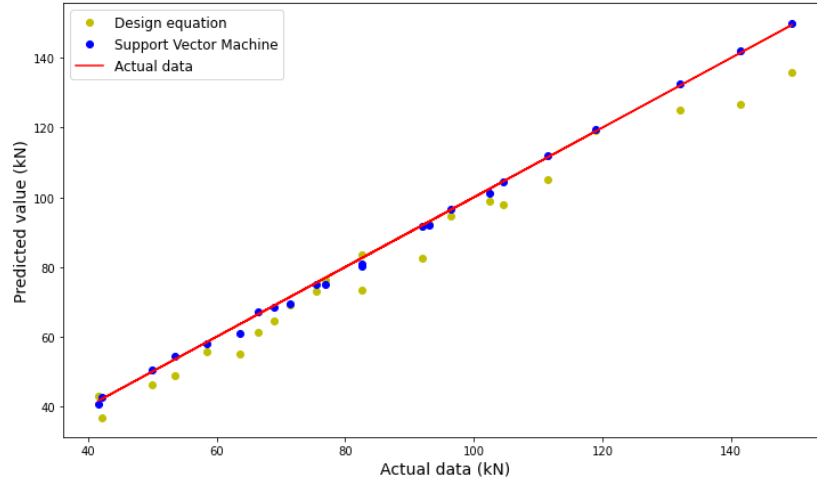


Figure 16: Comparison of the performance of Eq. (7) and SVR model in prediction of shear capacity of carbon steel LSBs.

464 equal to that of SVR model. However, the performance indicators are still
 465 found to be better when machine learning models are used. Additionally,
 466 Fig. 16 shows that the design equation predictions for carbon steel LSBs are
 467 deviated away from the actual data line with a considerably higher scatter
 468 than SVR model predictions. The design equation predictions appear to be
 469 slightly conservative for LSBs.

470 Therefore, the comparison suggests that the implemented four machine
 471 learning algorithms (SVR, MLP, GBR, and XGB) can be employed in accu-
 472 rate prediction of the shear capacity of steel channel sections. Even though,
 473 the existing design rules also seem to provide accurate predictions for the
 474 shear capacity, the improvement of machine learning predictions compared
 475 to the design rules can still be seen from the considered four performance
 476 indicators. In contrast to the available experimental and numerical methods
 477 which require greater deal of resources, the machine learning algorithms can
 478 be easily implemented as a tool in the decision making process to help civil or
 479 structural engineers. This study highlights the availability of machine learn-
 480 ing as an efficient and powerful tool, which can be implemented for accurate
 481 prediction of any section resistance of interest, given that adequate number
 482 of previous data is available.

483 6. Concluding remarks

484 This study presents the application of popular machine learning algo-
485 rithms in prediction of the shear resistance of steel channel sections. The ex-
486 perimental and numerical results of three-point loading tests of cold-formed
487 stainless steel LCBs and carbon steel LSBs are gathered from previous studies
488 and then employed in training machine learning algorithms. Support vector
489 regression, multi-layer perceptron, gradient boosting regressor, and extreme
490 gradient boosting algorithms were implemented in the study to predict the
491 shear capacity of steel channel sections using 108 results of LCBs and 238
492 results of LSBs. During the implementation of algorithms, pre-processing
493 of data, 10-fold cross-validation and hyperparameter tuning were performed.
494 The optimal hyperparameter combinations for each machine learning model
495 were found and the performance of the developed machine learning models
496 were evaluated based on performance indicators including linear correlation
497 coefficient, root mean square error, mean absolute error, and mean absolute
498 percentage error. Then, the performance of machine learning algorithms were
499 compared with the design equations predictions.

500 The developed SVR, MLP, GBR, and XGB machine learning models are
501 efficient and predicted well the shear capacity of both stainless steel LCBs
502 and carbon steel LSBs. The implemented SVR algorithm is proved to be
503 the best performing model in this study. Moreover, the evaluated perfor-
504 mance indicators for the design equations suggest fairly satisfactory results
505 giving conservative predictions. The implemented machine learning algo-
506 rithms are found to be performing better than the available design equations
507 in prediction of the shear capacities of stainless steel LCBs and carbon steel
508 LSBs. Therefore, this study highlights the applicability of machine learning
509 algorithms to solve similar structural and civil engineering problems when
510 carefully prepared data is present.

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